

Computer Graphics and Programming

Lecture 3

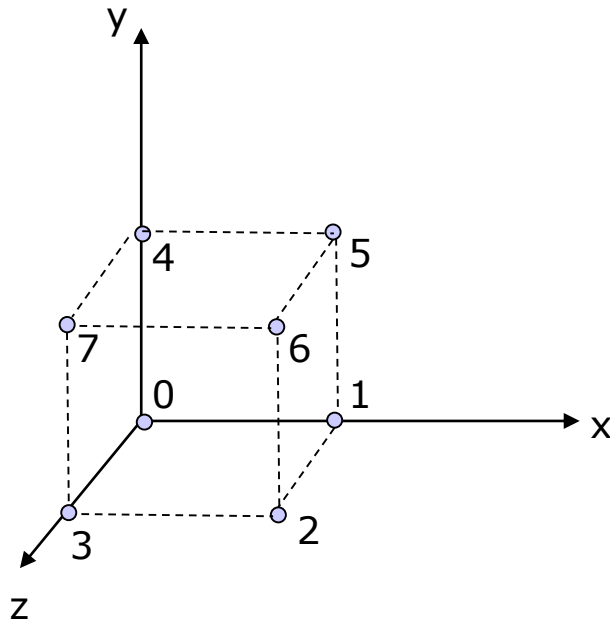
Perspective Projection Matrix

Jeong-Yean Yang

2020/10/22

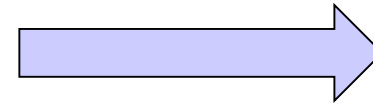
Projection from 3D into 2D

- Think box in 3D



$P0 = [0,0,0]$
 $P1 = [1,0,0]$
 $P2 = [1,0,1]$
 $P3 = [0,0,1]$
 $P4 = [0,1,0]$
 $P5 = [1,1,0]$
 $P6 = [1,1,1]$
 $P7 = [0,1,1]$

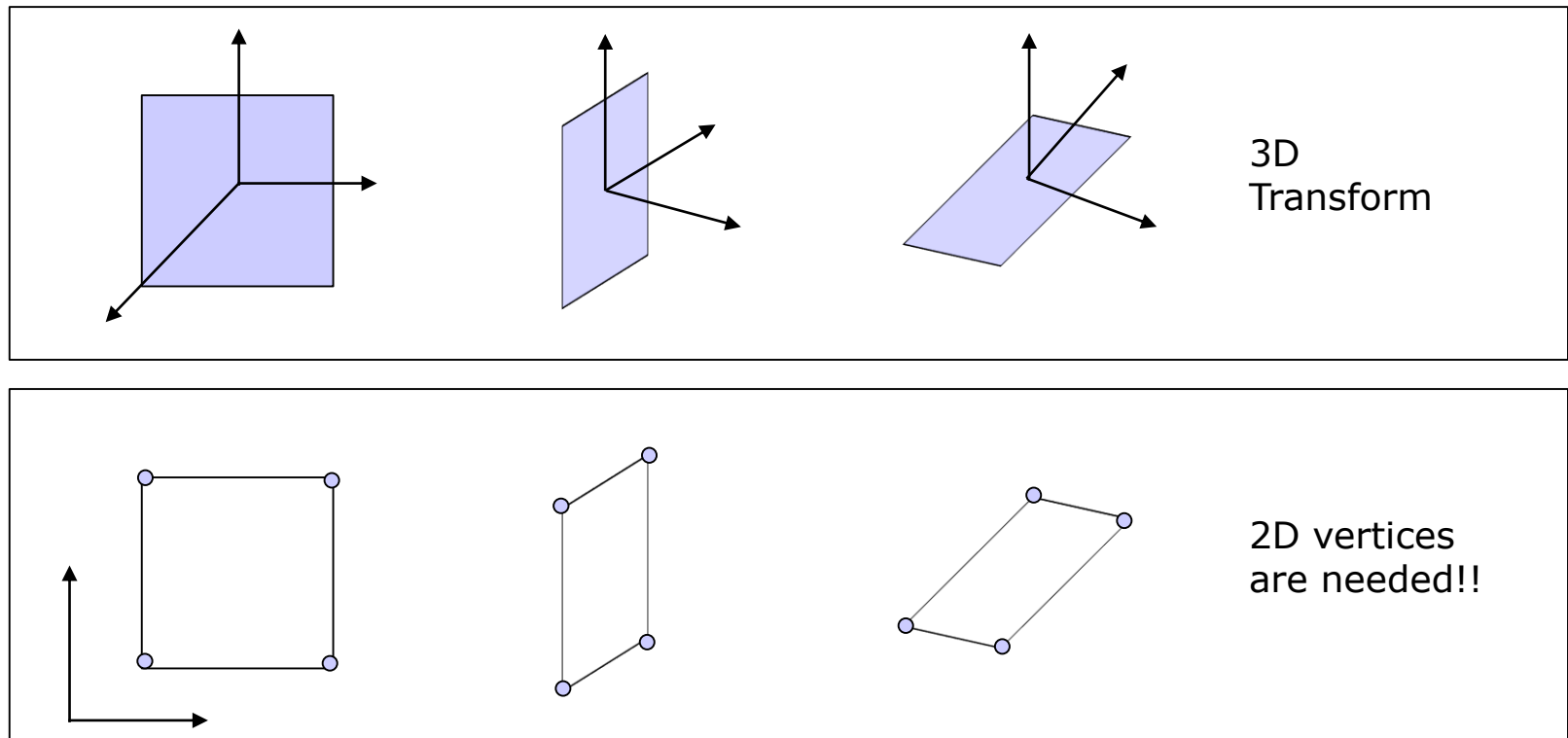
Homogeneous
Transform, H



$P0'$
 $P1'$
 $P2'$
 $P3'$
 $P4'$
 $P5'$
 $P6'$
 $P7'$

Question: How we get 2D points for line drawing?

Box Projection onto 2D Space



- Projection: Mapping from N dimensional space to $N-1$ dimensional space

Ref. Projection in Machine Learning



12시간 전

Car News 2019 | Top Gear
topgear.com



The Most Fuel-Efficient Cars - Consumer ...
consumerreports.org



2020 Chevy Spark Compact Car | Hatchback Car
chevrolet.com



The Best Time to Buy a Car - Tips for the ...
edmunds.com



Aston Martin | Iconic Luxury British ...
astonmartin.com



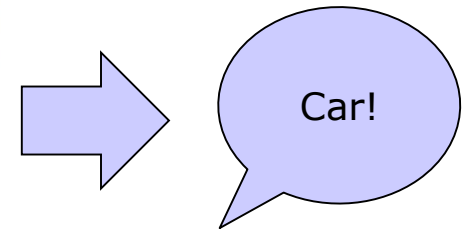
SIN is a Biomega electric car that is low-cost and I...
dezeen.com



Car News - Latest Car Reviews and Test Drives
popularmechanics.com



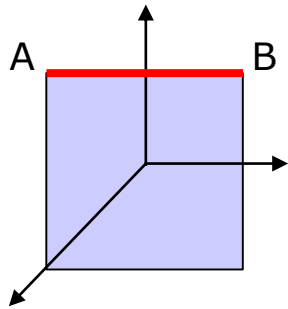
Auto powerhouse Slovakia eyes post-Brexit...
euractiv.com



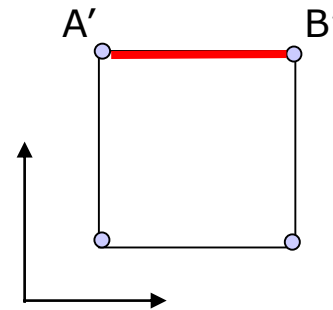
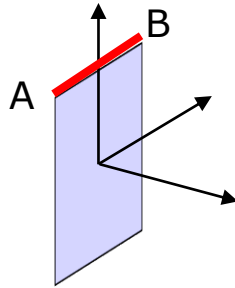
Car!

- Information in a High dimensional space is projected onto a lower dimensional space
 - Why? 4 wheels, engine, and so on.
- Starting point for Structuring Hierarchy

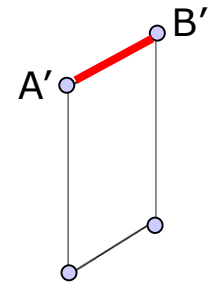
Characteristics of Projection



$$\|A - B\| = \text{const}$$



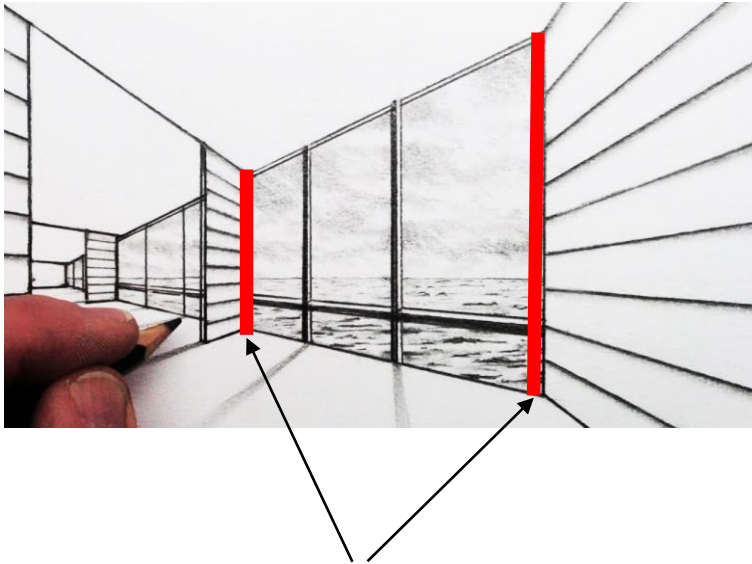
$$\|A' - B'\| \neq \text{const}$$



- 3D Space is a Euclidean Space.
- But, Projected Space is NOT a Euclidean Space.

Perspective Projection Matrix

- Perspective View



Two lines have Same Distance,
but these **look Different** in Perspective View



Who is the closest one?

It is not clear...
Big head...



Back to Homogeneous Transform

Why we call Homogeneity, 1?

$$H = \begin{bmatrix} R & T \\ 0 & 1 \end{bmatrix} \quad X = \begin{bmatrix} x \\ 1 \end{bmatrix}$$

$$X' = HX = \begin{bmatrix} R & T \\ 0 & 1 \end{bmatrix} \begin{bmatrix} x \\ 1 \end{bmatrix} = \begin{bmatrix} Rx + T \\ 1 \end{bmatrix}$$

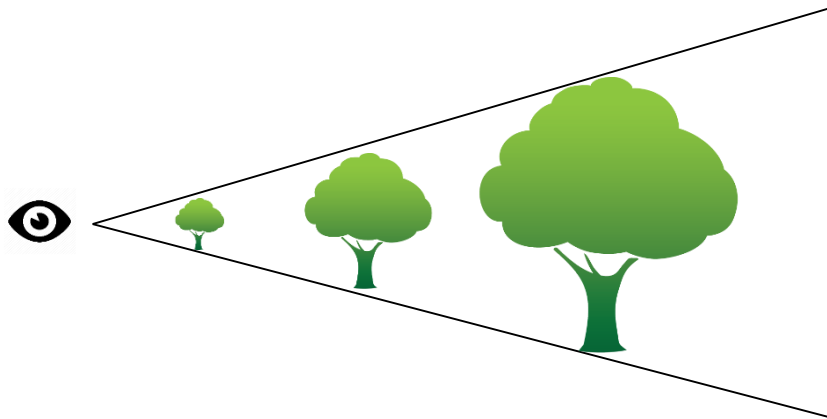
- We learn X has 1, which is needed for Homogeneous transform.
- **Why 1 is required?**

Homogeneity, 1 for Projection

- In a Homogeneous Space,

$$X \propto \begin{bmatrix} x \\ 1 \end{bmatrix} = \begin{bmatrix} 2x \\ 2 \end{bmatrix} = \begin{bmatrix} hx \\ h \end{bmatrix}$$

- It is NOT a general vector space
- It is a Affine Space



Everything looks same!

Vector or Point

- Homogeneous Transform requires

$$X = \begin{bmatrix} x \\ h \end{bmatrix} \quad h=0 \text{ or } 1$$

$$X_1 = \begin{bmatrix} x_1 \\ 1 \end{bmatrix}, X_2 = \begin{bmatrix} x_2 \\ 1 \end{bmatrix}$$

$$X_1 - X_2 = \begin{bmatrix} x_1 - x_2 \\ 1 - 1 \end{bmatrix} = \begin{bmatrix} x_1 - x_2 \\ 0 \end{bmatrix}$$

Point-Point = Vector

$$X_1 = \begin{bmatrix} x_1 \\ 0 \end{bmatrix}, X_2 = \begin{bmatrix} x_2 \\ 0 \end{bmatrix}$$

$$X_1 - X_2 = \begin{bmatrix} x_1 - x_2 \\ 0 \end{bmatrix}$$

Vector-Vector = Vector

Definition of Vector and Point

$$\text{Vector, } V = \begin{bmatrix} x \\ 0 \end{bmatrix}, \quad \text{Point, } P = \begin{bmatrix} x \\ 1 \end{bmatrix}$$

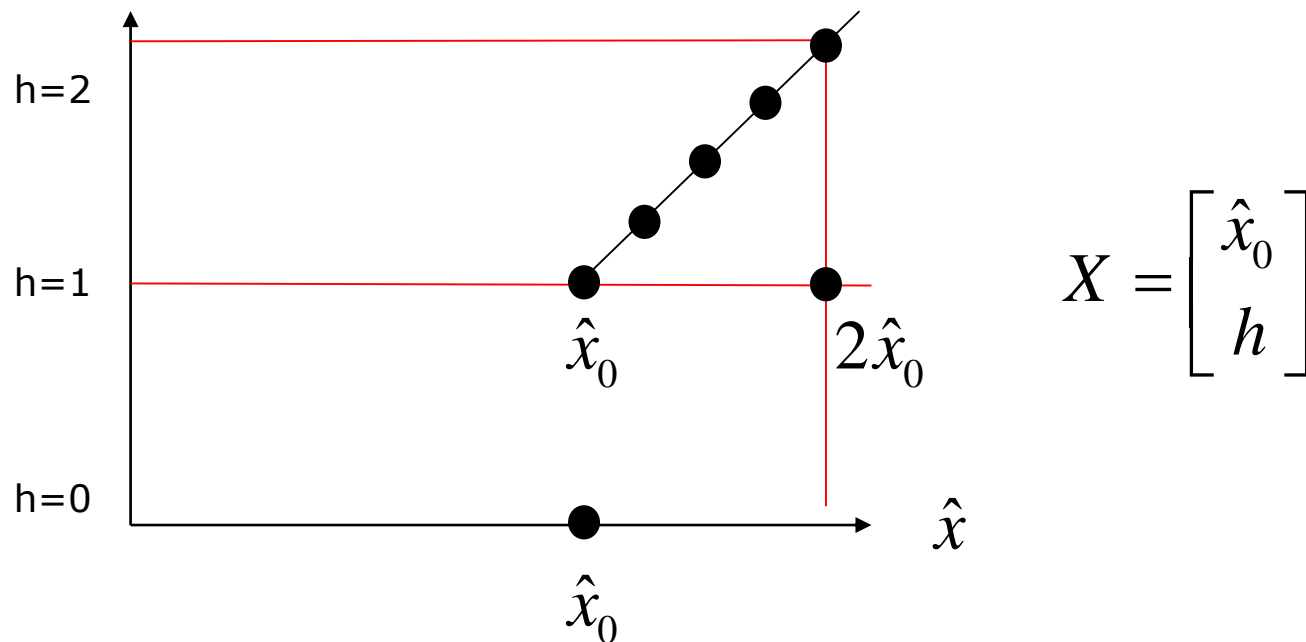
- So, 0 or 1 is the only case?

$$P = \begin{bmatrix} x \\ 0.3 \end{bmatrix} \quad \text{What is it?}$$

- It is a **Point**.

$$P = \begin{bmatrix} x \\ 0.3 \end{bmatrix} = \begin{bmatrix} x/0.3 \\ 1 \end{bmatrix}$$

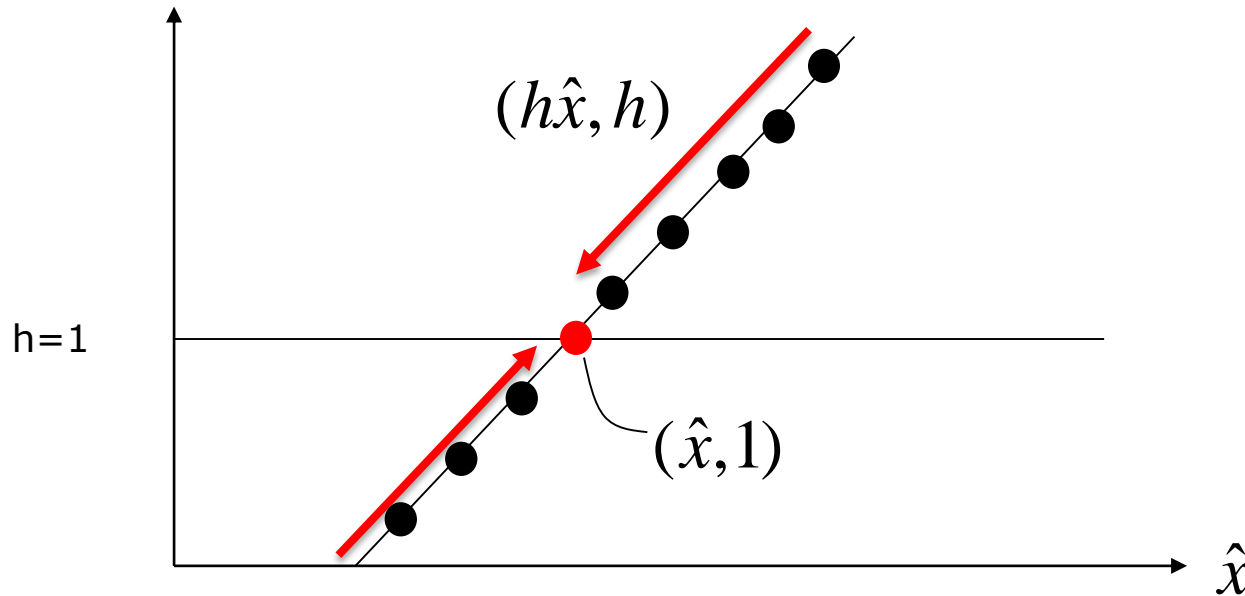
Truth of Homogeneous Transform



- In a Homogeneous Space,
 - Design this space as,
 - Every Vector is projected on $h=0$
 - Every point is projected on $h=1$

$$X = \begin{bmatrix} \hat{x}_0 \\ 1 \end{bmatrix} = \begin{bmatrix} 2\hat{x}_0 \\ 2 \end{bmatrix} = \begin{bmatrix} 0.1\hat{x}_0 \\ 0.1 \end{bmatrix}$$

Homogeneous \rightarrow Projection on $h=1$



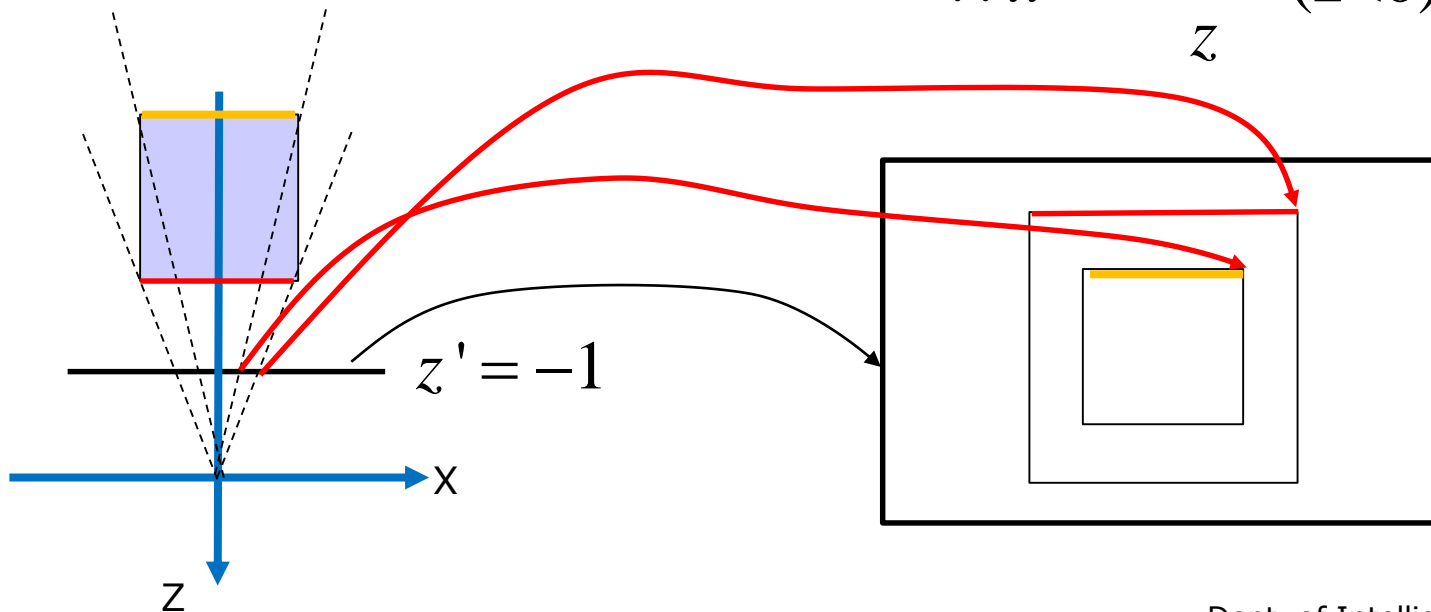
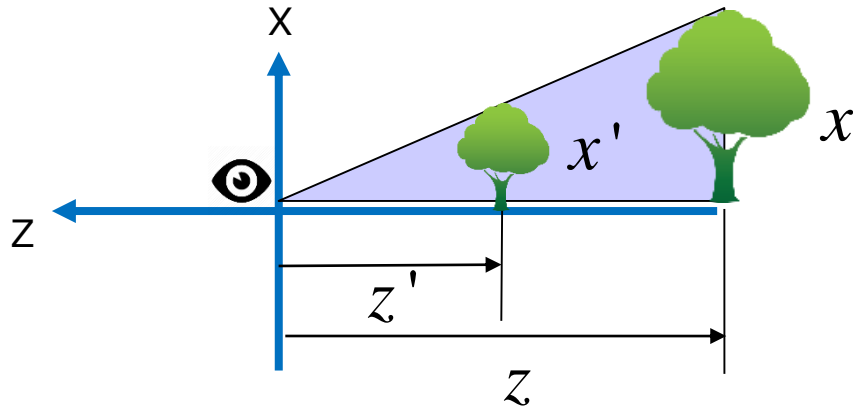
- All points passing $(\hat{x}, 1)$ are same.
- All points passing $(h\hat{x}, h)$ are projected on $(\hat{x}, 1)$

Example) Perspective View

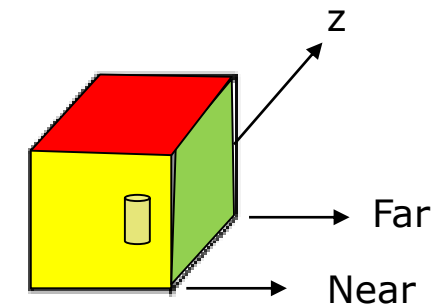
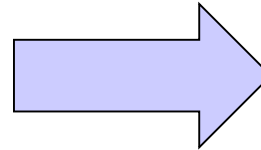
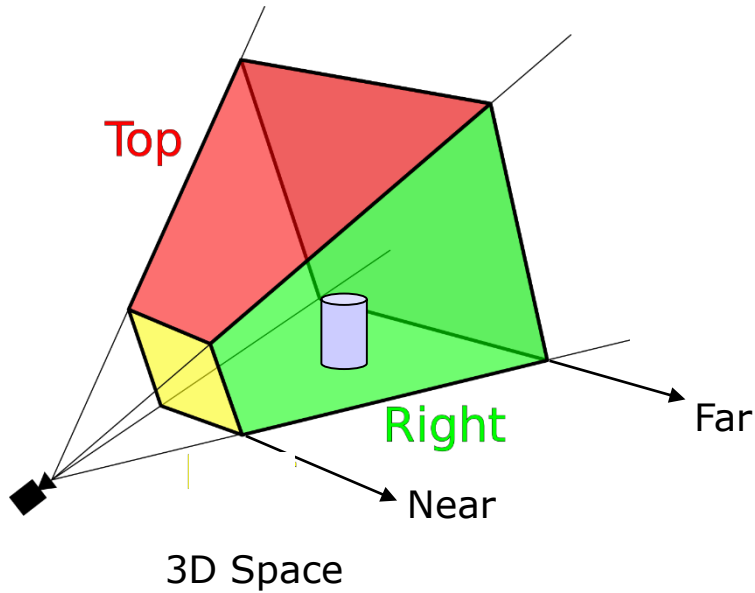
$$\frac{x'}{z'} = \frac{x}{z} \quad (z', z < 0)$$

if we define $z' = -1$,

$$\therefore x' = -\frac{x}{z} \quad (z < 0)$$

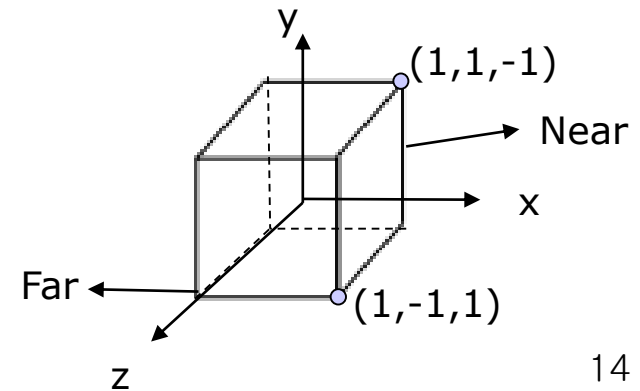


Modeling of Perspective View uses Viewing Pyramid(Frustum)

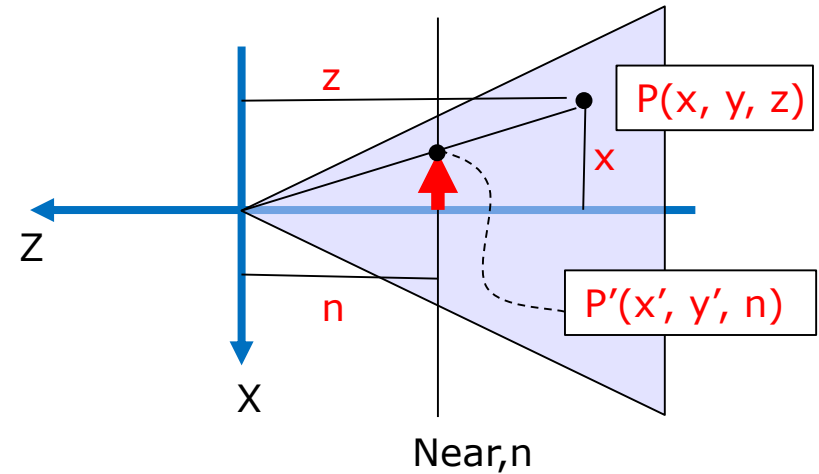
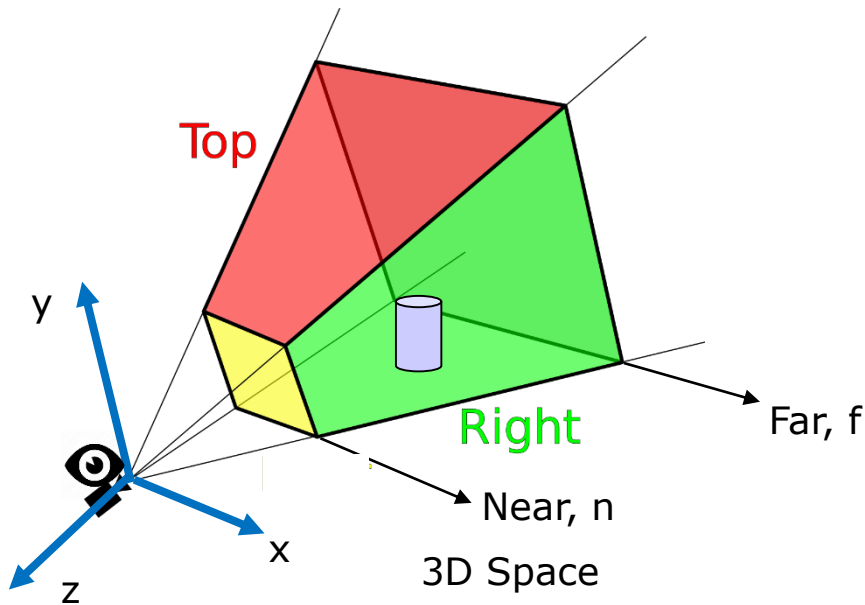


$$W=H=T=[-1,1]$$

Unit Space



Basic Perspective View to Z axis



- Calculate $P'(x', y', n)$ on near plane from $P(x, y, z)$

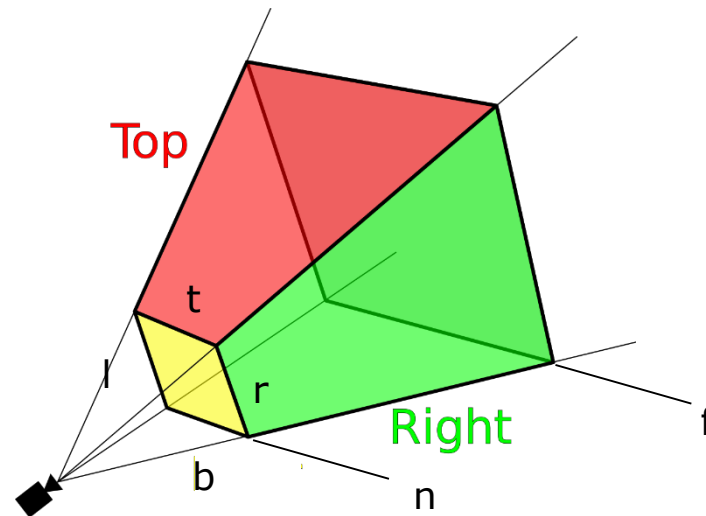
$$\frac{\uparrow}{n} = \frac{x'}{n} = \frac{x}{z} \quad (n, z < 0) \quad \therefore x' = n \frac{x}{z}$$

- Top of Pyramid is “Origin”, at which the Eye locates. ¹⁵



Definition of Perspective Projection

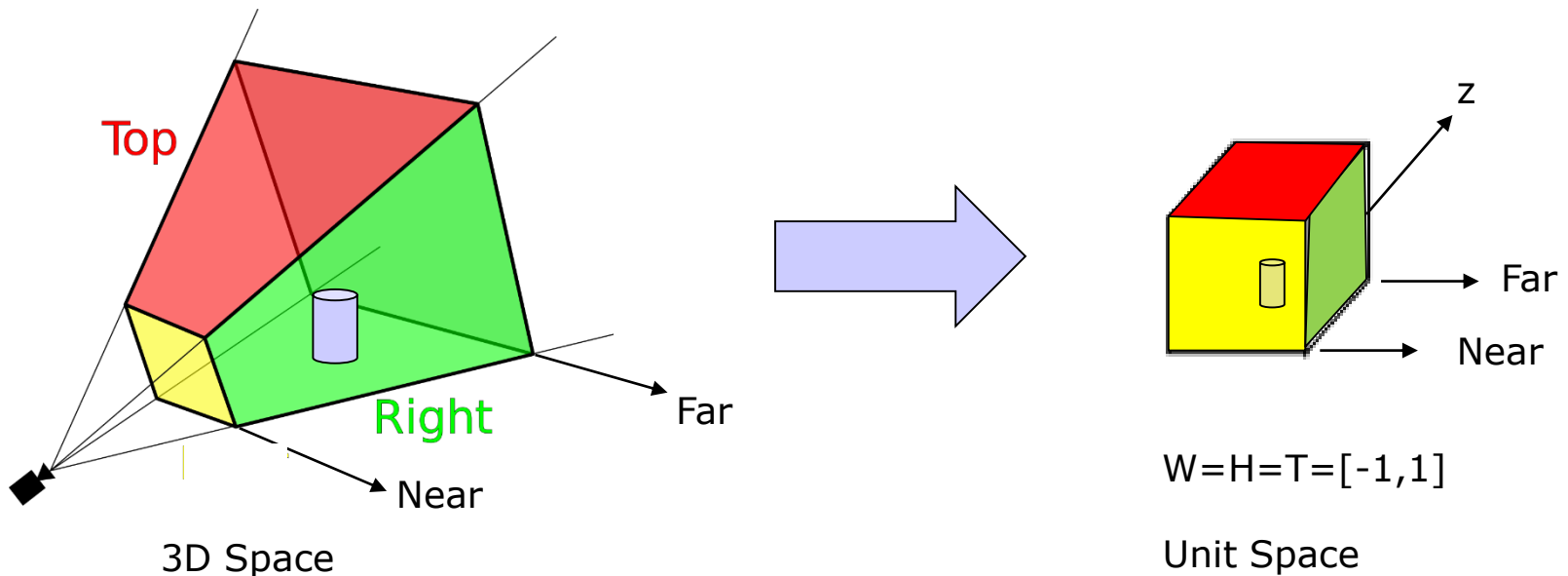
- Perspective Projection
 - Window size of **near plane** is **l, r, t, b**.



1. Perspective Mapping

Objects in the Frustum are mapped into the unit space

- Recall that



- Near plane : $z = -1$ ($\rightarrow n = -1$)
- Map x to $\frac{x}{-z}$ and map y to $\frac{y}{-z}$

$$\begin{array}{l} x' = -\frac{x}{z} \\ pp. 13 \end{array}$$

Derivation of Perspective Mapping (Original Derivation)

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} e & 0 & 0 & 0 \\ 0 & f & 0 & 0 \\ 0 & 0 & a & c \\ 0 & 0 & b & d \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} ex \\ fy \\ az + c \\ bz + d \end{pmatrix} = \begin{pmatrix} \frac{ex}{bz + d} \\ \frac{fy}{bz + d} \\ \frac{az + c}{bz + d} \\ 1 \end{pmatrix}$$

$a, b, c, d, e, f = ?$

To map x to $x' = \frac{x}{-z}$ ($z < 0$), $\frac{ex}{bz + d} \rightarrow e = 1, b = -1, d = 0$

To map y to $y' = \frac{y}{-z}$ ($z < 0$), $\frac{fy}{bz + d} \rightarrow f = 1, b = -1, d = 0$

$$\therefore z' = \frac{az + c}{bz + d} = \frac{az + c}{-z}$$

Derivation of Perspective Mapping (Short Derivation)

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & a & c \\ 0 & 0 & b & d \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ az + c \\ bz + d \end{pmatrix} = \begin{pmatrix} \frac{x}{bz + d} \\ \frac{y}{bz + d} \\ \frac{az + c}{bz + d} \\ 1 \end{pmatrix}$$

$a, b, c, d = ?$

To map x to $x' = \frac{x}{-z}$, $\frac{x}{bz + d} \rightarrow b = -1, d = 0$

To map y to $y' = \frac{y}{-z}$, $\frac{y}{bz + d} \rightarrow b = -1, d = 0$

$$\therefore z' = \frac{az + c}{bz + d} = \frac{az + c}{-z}$$

Think Z in Near Plane and Far plane

$$\therefore z' = \frac{az + c}{bz + d} = \frac{az + c}{-z} \quad (z < 0)$$

if $n, f > 0$

if $z = -n$, then $z' = -1$

$$\therefore z' = -1 = \frac{-an + c}{n}$$

$$-an + c = -n$$

if $z = -f$, then $z' = 1$

$$\therefore z' = 1 = \frac{-af + c}{f}$$

$$f = -af + c$$

$$f = -af - n + an$$

$$c = (a - 1)n$$

$$\therefore a = \frac{n + f}{n - f}$$

$$\therefore c = \left(\frac{n + f}{n - f} - 1 \right) n = \frac{2nf}{n - f}$$



Perspective Matrix

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & a & c \\ 0 & 0 & b & d \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$

$$\textit{Perspective Matrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

Normalization of Perspective Matrix Result

$$\begin{aligned}
 \begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} &= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \frac{n+f}{n-f} + \frac{2nf}{n-f} \\ -z \end{pmatrix} \\
 &= \begin{pmatrix} \frac{x}{-z} & \frac{y}{-z} & \frac{z(n+f) + 2nf}{-z(n-f)} & 1 \end{pmatrix}^T \quad (z < 0)
 \end{aligned}$$

See uWnd-19-3D-Perspective-Projection

- uObj::Draw line 39

$$\hat{x}' = P\hat{x} = \begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \frac{n+f}{n-f} + \frac{2nf}{n-f} \\ -z \end{pmatrix} \quad (z < 0)$$

```
// transform vertex
```

```
for (i=0;i<nMax;i++)
```

```
{
    temp[i] = H*vertex[i];
```

```
    float z = temp[i].z;
```

```
    temp[i] = P*temp[i];
```

```
    temp[i].x = -temp[i].x/z;
```

```
    temp[i].y = -temp[i].y/z;
```

```
    temp[i].z = -temp[i].z/z;
```

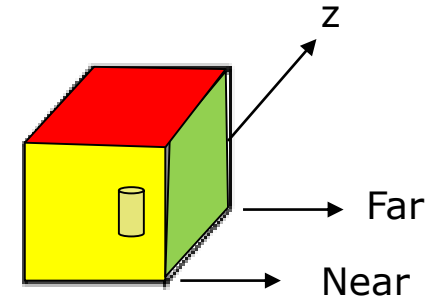
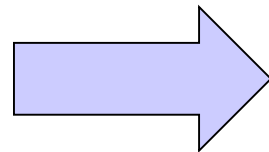
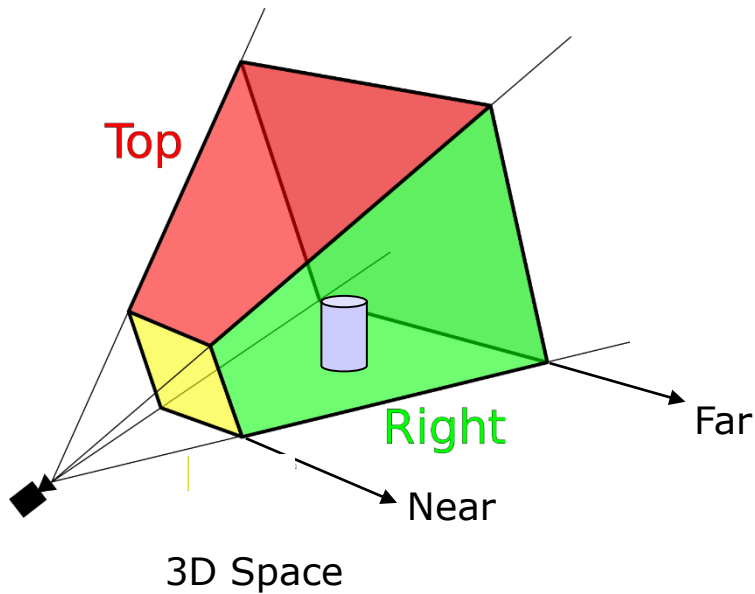
```
    temp[i] = S*temp[i];
```

```
}
```

$$= \begin{pmatrix} x & y & z(n+f) + 2nf & 1 \\ -z & -z & -z(n-f) & 1 \end{pmatrix}^T \quad (z < 0)$$

Example 1.

Calculation of Perspective Projection Mapping

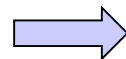


$$W=H=T=[-1,1]$$

Unit Space

$$P = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

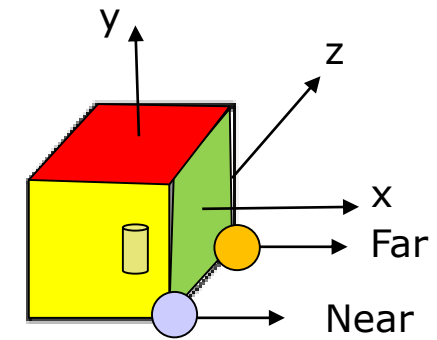
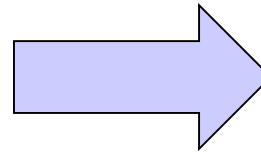
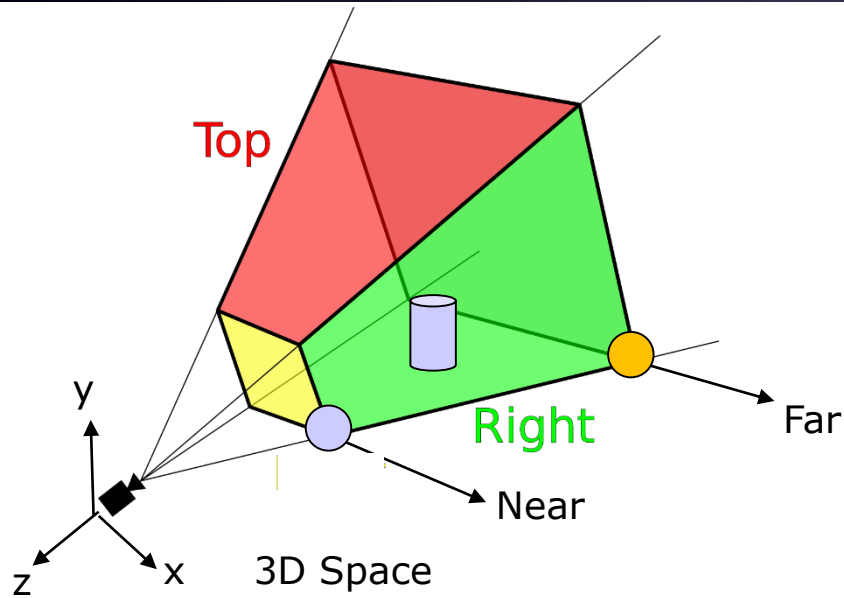
$$n, f > 0$$



Assume that
 $n = 1$
 $f = 65535$

$$P \cong \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & -2 \\ 0 & 0 & -1 & 0 \end{pmatrix}$$





$$W=H=T=[-1,1]$$

Unit Space

● $X = (1, -1, -1, 1)^T$

$$X = PX = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & -2 \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} 1 \\ -1 \\ -1 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ -1 \\ \underline{-1} \\ 1 \end{pmatrix}$$

● $X = (65535, -65535, -65535, 1)^T$

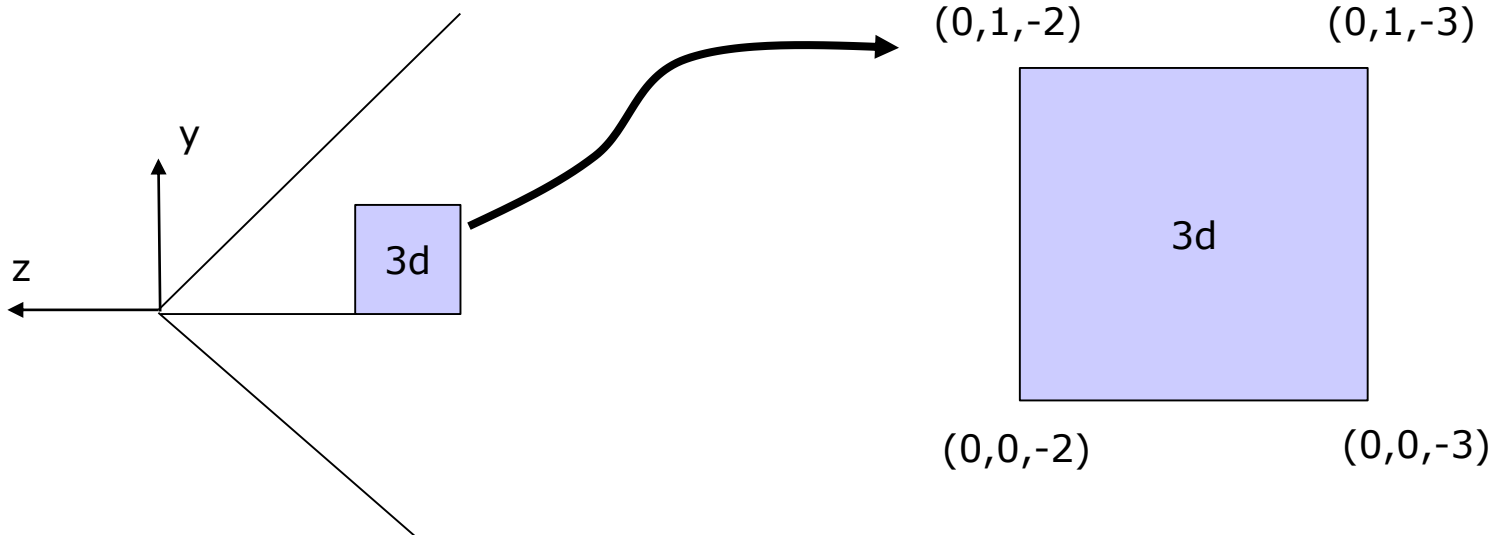
$$= (f, -f, -f, 1)^T$$

$$X = PX = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & -2 \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} f \\ -f \\ -f \\ 1 \end{pmatrix} = \begin{pmatrix} f \\ -f \\ f-2 \\ f \end{pmatrix}$$

$$= \begin{pmatrix} \frac{f}{f} & \frac{-f}{f} & \frac{f-2}{f} & 1 \end{pmatrix}^T \cong (1 \quad -1 \quad \underline{1} \quad 1)^T$$

Example 2.

From 3D to 2D



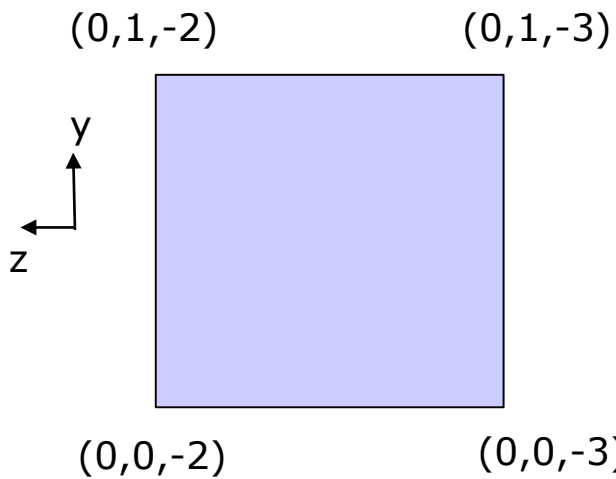
$$P \cong \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & -1 & -2 \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

$$P(0 \ 1 \ -2 \ 1)^T = (0 \ 1 \ 0 \ 2)^T$$

$$P(0 \ 0 \ -2 \ 1)^T = (0 \ 0 \ 0 \ 2)^T$$

$$P(0 \ 1 \ -3 \ 1)^T = (0 \ 1 \ 1 \ 3)^T$$

$$P(0 \ 0 \ -3 \ 1)^T = (0 \ 0 \ 1 \ 3)^T$$



pp.23

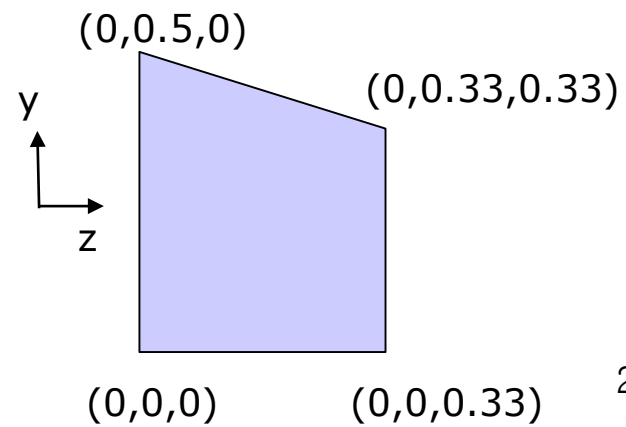
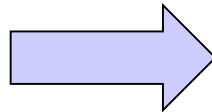
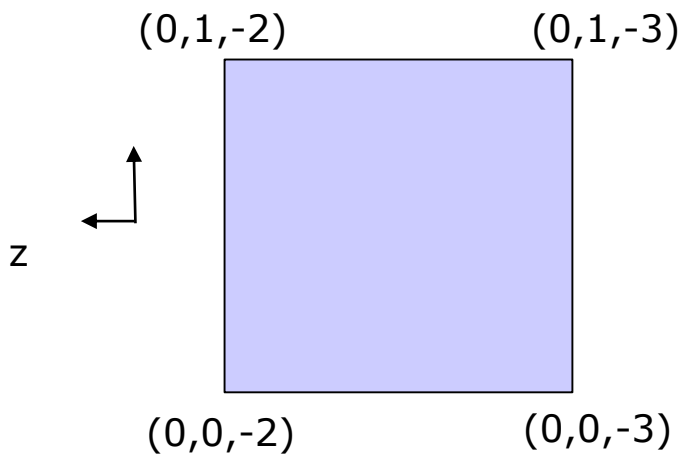
$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix} = \begin{pmatrix} x \\ y \\ z \frac{n+f}{n-f} + \frac{2nf}{n-f} \\ -z \end{pmatrix} \quad (z < 0)$$

$$P(0 \ 1 \ -2 \ 1)^T = (0 \ 1 \ 0 \ 2)^T = (0 \ 0.5 \ 0 \ 1)^T \quad (z = -2 < 0)$$

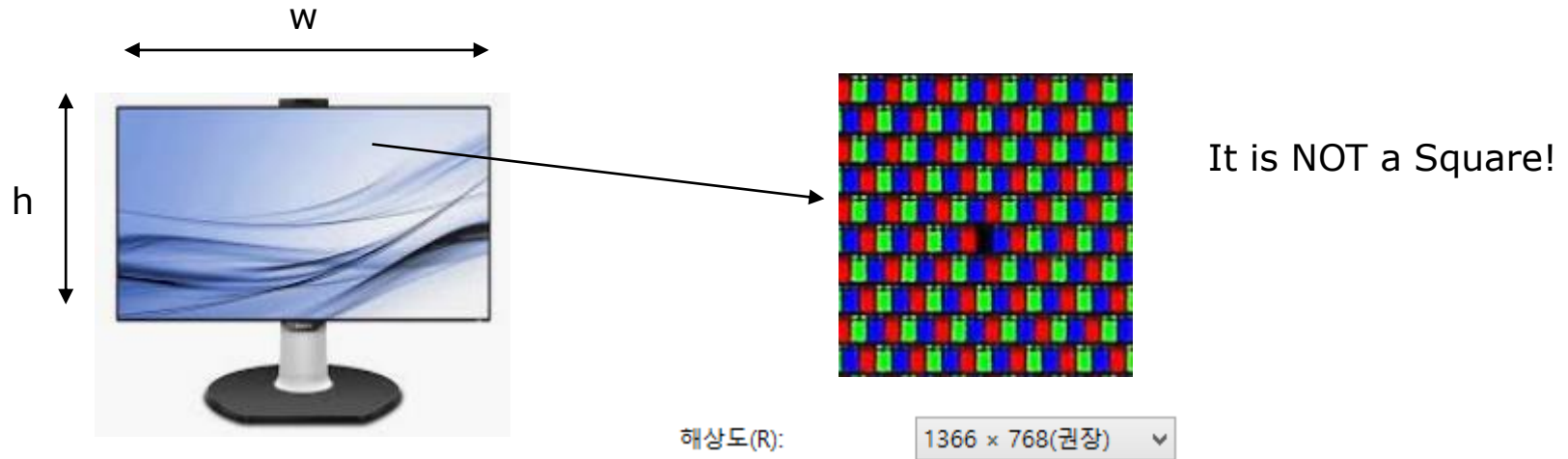
$$P(0 \ 0 \ -2 \ 1)^T = (0 \ 0 \ 0 \ 2)^T = (0 \ 0 \ 0 \ 1)^T \quad (z = -2 < 0)$$

$$P(0 \ 1 \ -3 \ 1)^T = (0 \ 1 \ 1 \ 3)^T = (0 \ 0.33 \ 0.33 \ 1)^T \quad (z = -3 < 0)$$

$$P(0 \ 0 \ -3 \ 1)^T = (0 \ 0 \ 1 \ 3)^T = (0 \ 0 \ 0.33 \ 1)^T \quad (z = -3 < 0)$$

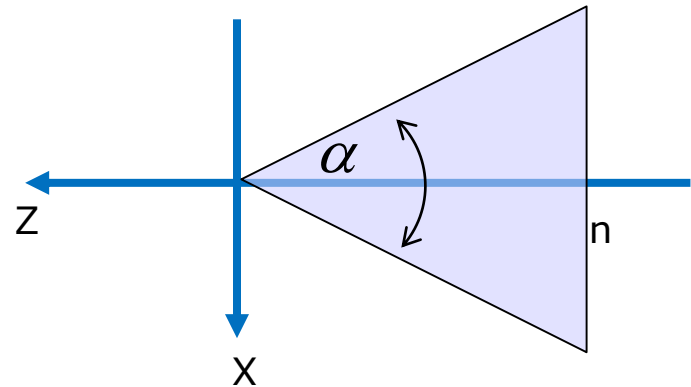
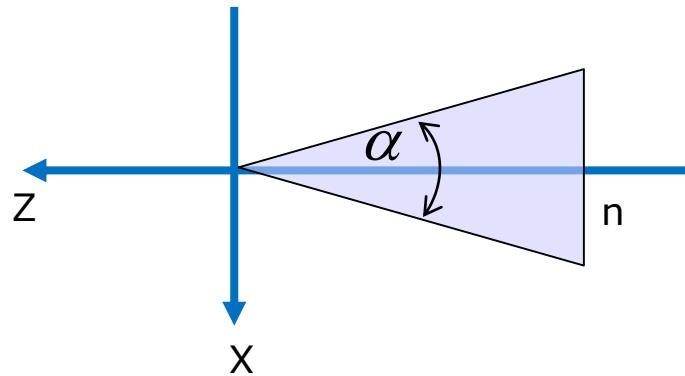


2. Aspect Ratio



- Aspect ratio = width/height
 - Ex) AR = 1366/768

3. Field of View (FOV)



$$x' = \frac{n}{r-l} x = x \cot \frac{\alpha}{2}$$

$$y' = \frac{n}{t-b} y = y \cot \frac{\alpha}{2}$$

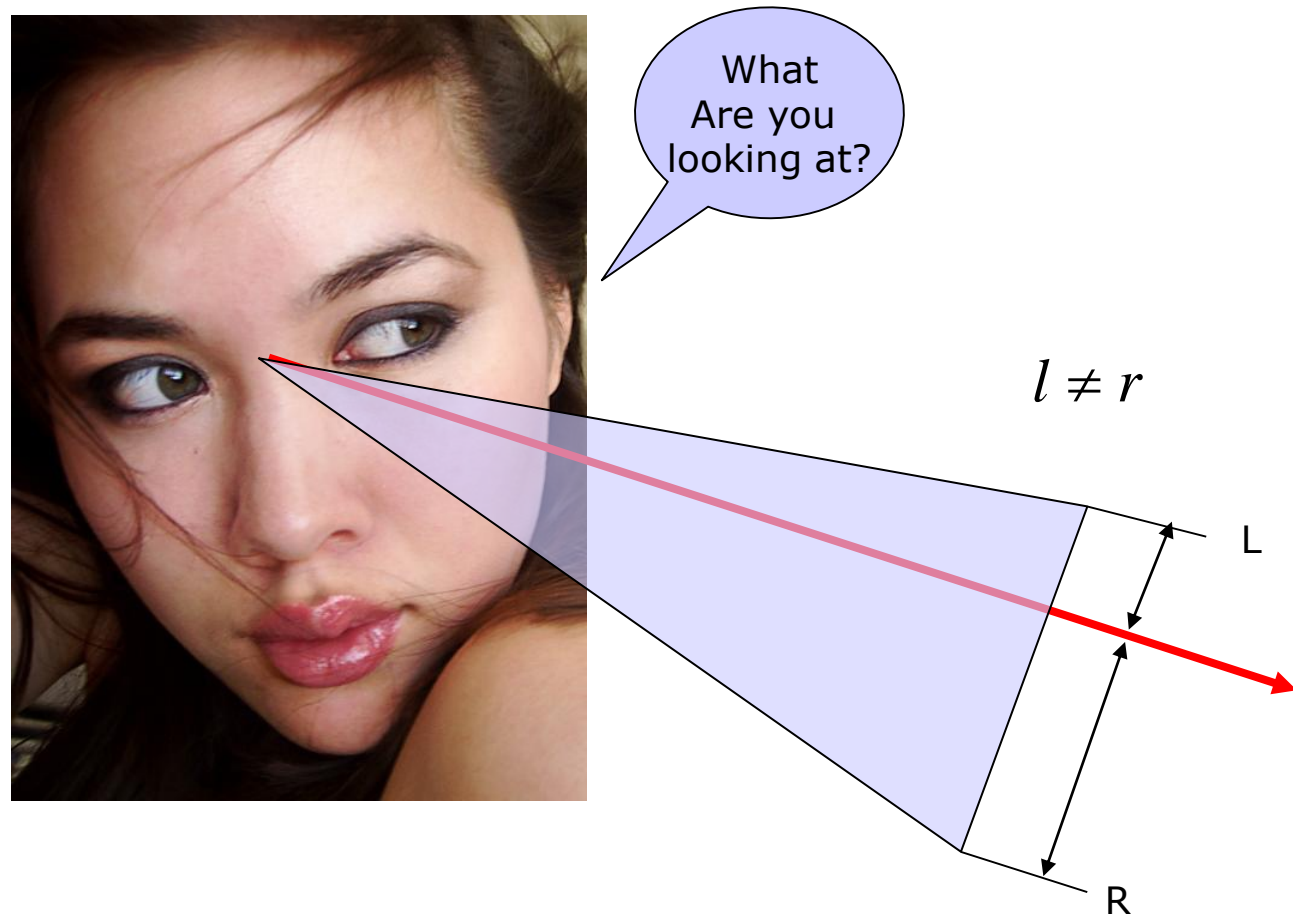
4. Aspect Ratio and FOV are applied

$$P = \begin{pmatrix} \frac{\cot(\alpha / 2)}{W / H} & 0 & 0 & 0 \\ 0 & \cot(\alpha / 2) & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

- This matrix is same with gluPerspective in OpenGL
 - $n = 1$ and $f=65535$
- Keep in mind \rightarrow gluPerspective is deprecated in OpenGL ES.

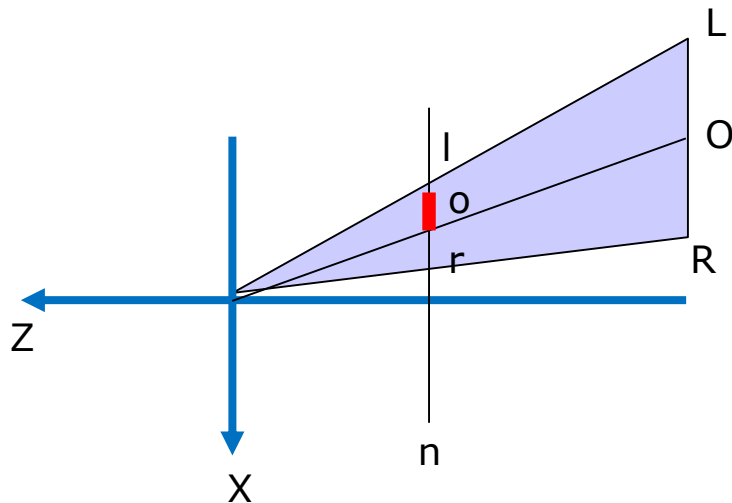


Special Cases: Condition that Frustum is Skewed, Shearing and Clipping are Needed.



- Skewed projection becomes Popular in VR.

5. Shearing Window to Z axis



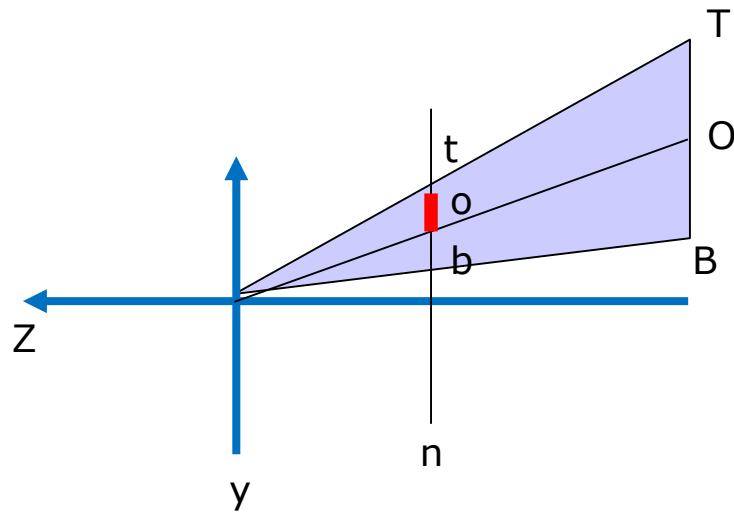
$$\frac{l}{n} = \frac{L}{z}, \frac{r}{n} = \frac{R}{z}$$

$$o = \frac{l+r}{2} = n \frac{\frac{L}{z} + \frac{R}{z}}{2} = \frac{n}{z} \frac{L+R}{2} = \frac{n}{z} O$$

$$x' = x - |O|$$

$$x' = x + O = x + \frac{z}{n} o = x + \frac{l+r}{2} \frac{z}{n}$$

5. Shearing Window to Z axis



$$\frac{t}{n} = \frac{T}{z}, \frac{b}{n} = \frac{B}{z}$$

$$o = \frac{t+b}{2} = n \frac{\frac{T}{z} + \frac{B}{z}}{2} = \frac{n}{z} \frac{T+B}{2} = \frac{n}{z} O$$

$$y' = y + |O|$$

$$y' = y + O = y + \frac{z}{n} o = y + \frac{t+b}{2} \frac{z}{n}$$

5. Shearing Window Matrix

$$x' = x + O_x = x + \frac{z}{n} o_x = x + \frac{l+r}{2} \frac{z}{n}$$

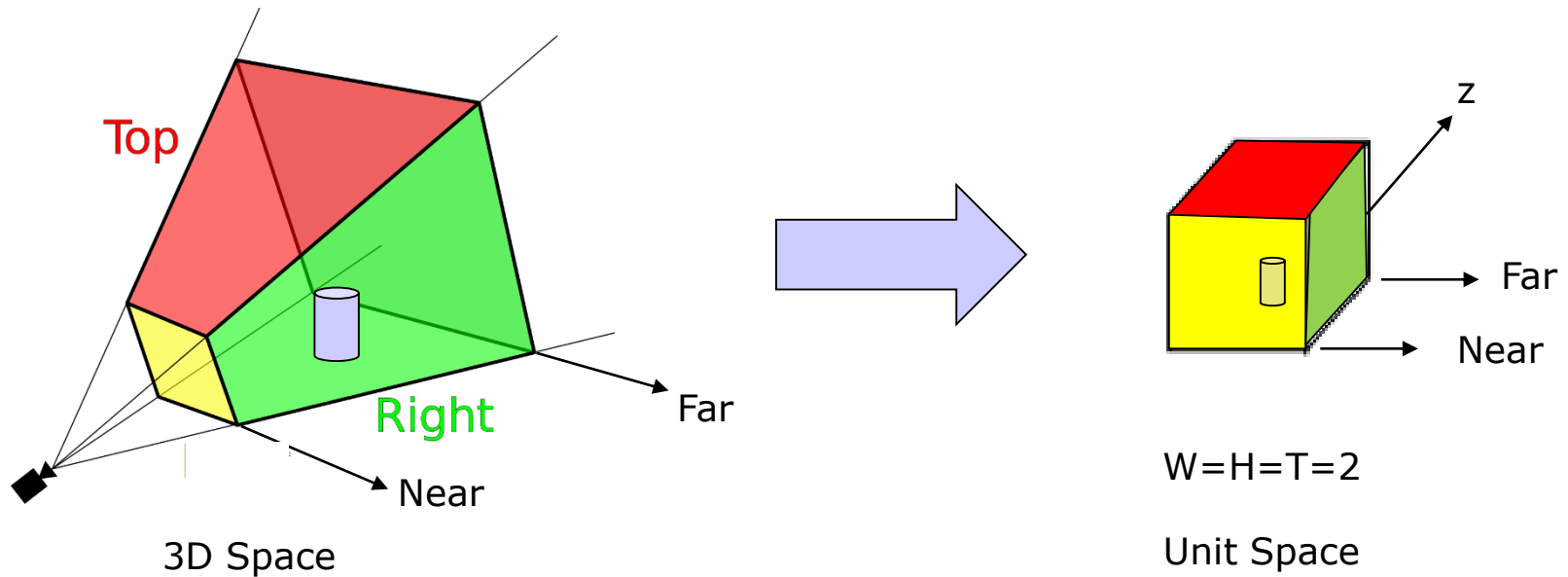
$$y' = y + O_y = y + \frac{z}{n} o_y = y + \frac{t+b}{2} \frac{z}{n}$$

$$z' = z$$

- Shearing Window Matrix in Homogeneous Transform

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} 1 & 0 & \frac{l+r}{2n} & 0 \\ 0 & 1 & \frac{t+b}{2n} & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$

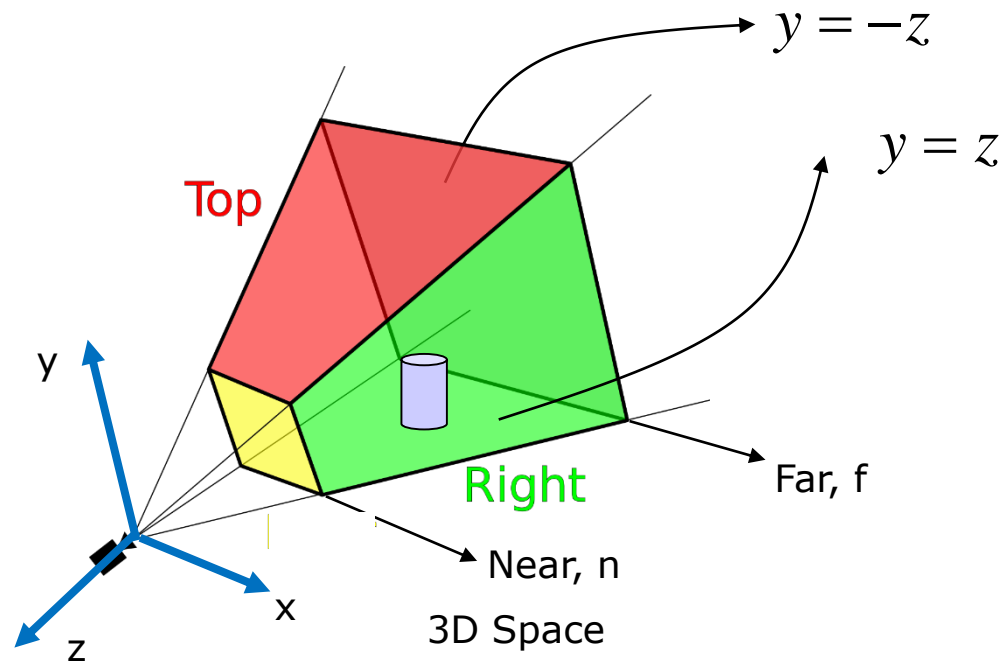
6. Clipping Boundaries



- Clipping object and Mapping into Unit space
 - Width= $[-1,1]$
 - Height= $[-1,1]$
 - Thickness= $[-1,1]$

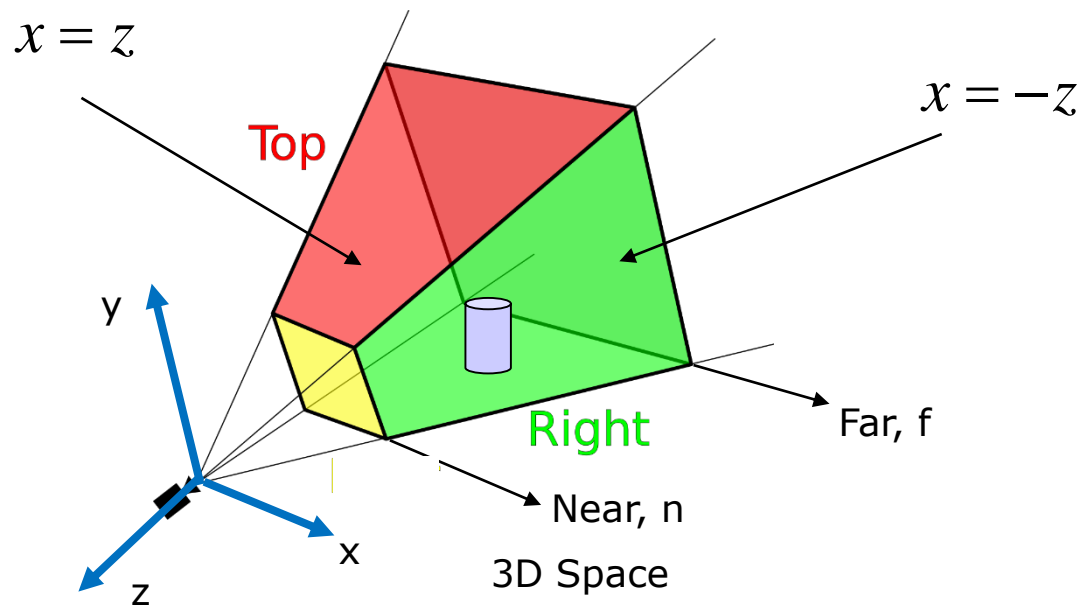
6. Clipping Boundaries

- Think plane



6. Clipping Boundaries

- Think plane



6. Clipping Boundaries

- Clipping boundaries into Unit Space [-1,1]

$$x' = \frac{2n}{r-l} x$$

$$y' = \frac{2n}{t-b} y$$

$$z' = z$$

$$r = 1$$

$$l = -1$$

$$t = 1$$

$$b = -1$$

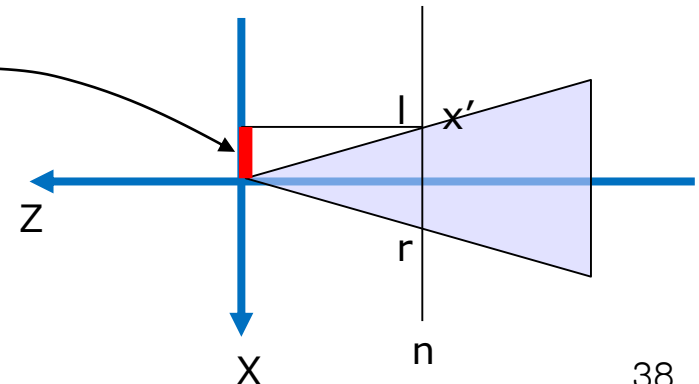
$$n = 1$$

$$x' = x$$

$$y' = y$$

$$z' = z$$

$$\begin{pmatrix} x' \\ y' \\ z' \\ 1 \end{pmatrix} = \begin{pmatrix} \frac{2n}{r-l} & 0 & 0 & 0 \\ 0 & \frac{2n}{t-b} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \\ z \\ 1 \end{pmatrix}$$



7. Skewed Perspective Projection matrix

$P = \text{Perspective} \times \text{Clipping} \times \text{Shearing}$

$$= \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix} \begin{pmatrix} \frac{2n}{r-l} & 0 & 0 & 0 \\ 0 & \frac{2n}{t-b} & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 0 & \frac{l+r}{2n} & 0 \\ 0 & 1 & \frac{t+b}{2n} & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} \frac{2n}{r-l} & 0 & \frac{r+l}{r-l} & 0 \\ 0 & \frac{2n}{t-b} & \frac{t+b}{t-b} & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

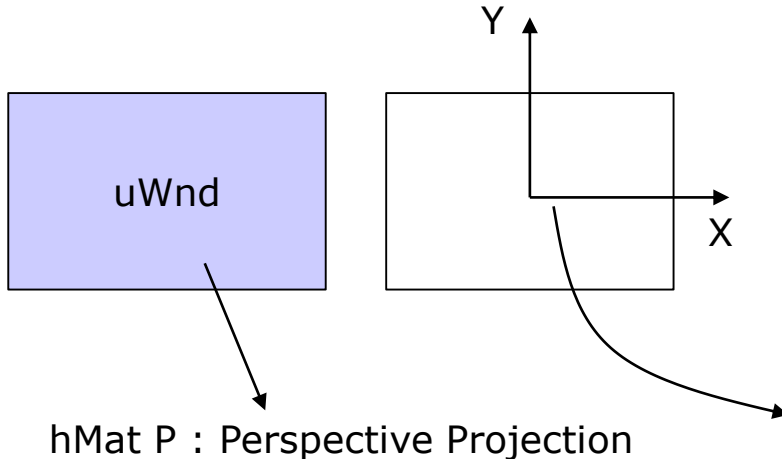
$$\begin{matrix} r=1 \\ l=-1 \\ t=1 \\ b=-1 \\ n=1 \end{matrix} \rightarrow \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$

Skewed Perspective Projection

Perspective Projection



Ex) uWnd-19-3D-Perspective-Projection



```
float n=1;
float f=65535;
float angle    = 90;
float aspect   = 1366./768;

float z1 = (n+f)/(f-n);
float z2 = (n*f)/(f-n);
float ct = 1./tan(RAD(angle)/2);

P.v[0]  = ct/aspect;
P.v[5]  = ct;
P.v[10] = -z1;
P.v[11] = -1;
P.v[14] = -2*z2;
P.v[15] = 1;
```

```
void uWnd::OnPaint()
{
    CPaintDC dc(this);
    CDC *pDC = &dc;

    CRect rect;
    GetClientRect(rect);
    pDC->SetMapMode(MM_ANISOTROPIC);
    pDC->SetWindowExt(rect.Width()/2,rect.Height()/2);
    pDC->SetViewportExt( rect.Width()/2,-rect.Height()/2);
    pDC->SetViewportOrg( rect.Width()/2, rect.Height()/2);

    Draw(pDC);
}
```

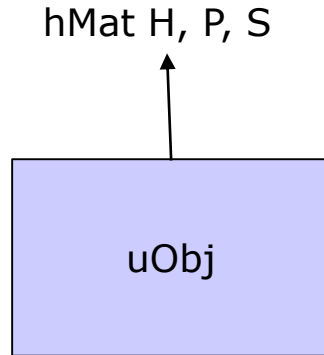
pp. 23

$$hMat = \begin{bmatrix} v[0] & v[4] & v[8] & v[12] \\ v[1] & v[5] & v[9] & v[13] \\ v[2] & v[6] & v[10] & v[14] \\ v[3] & v[7] & v[11] & v[15] \end{bmatrix}$$

$$P = \begin{pmatrix} \frac{\cot(\alpha/2)}{W/H} & 0 & 0 & 0 \\ 0 & \cot(\alpha/2) & 0 & 0 \\ 0 & 0 & \frac{n+f}{n-f} & \frac{2nf}{n-f} \\ 0 & 0 & -1 & 0 \end{pmatrix}$$



3D Object Building

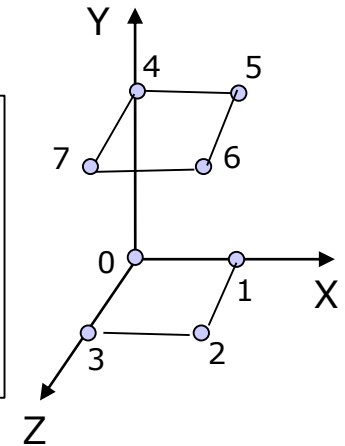


H: Object transform

P: Perspective
Projection

S: Scaling

```
vertex[0] = uVector(0,0,0);
vertex[1] = uVector(1,0,0);
vertex[2] = uVector(1,1,0);
vertex[3] = uVector(0,1,0);
vertex[4] = uVector(0,0,1);
vertex[5] = uVector(1,0,1);
vertex[6] = uVector(1,1,1);
vertex[7] = uVector(0,1,1);
```



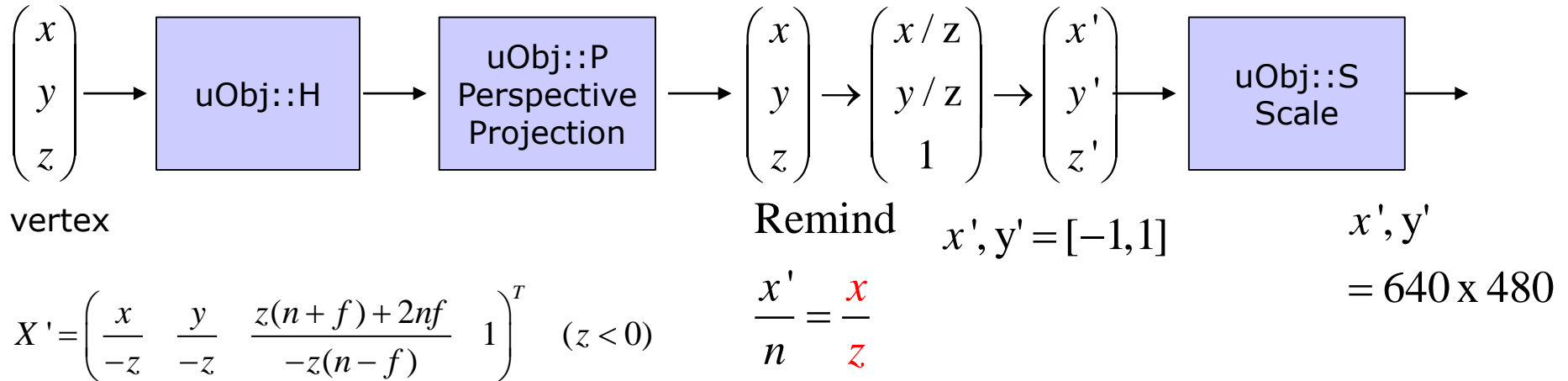
Polygon with 3 vertices

```
void uObj::DrawPolygon(CDC *pDC, uVector f,uVector s,uVector t)
{
    pDC->MoveTo(f.x,f.y);
    pDC->LineTo(s.x,s.y);
    pDC->LineTo(t.x,t.y);
    pDC->LineTo(f.x,f.y);
}
```

Draw Counter Clock Wise

```
DrawPolygon(pDC, temp[6],temp[2],temp[1]); //right
DrawPolygon(pDC, temp[6],temp[1],temp[5]);
```

Drawing with Perspective Projection



$\begin{pmatrix} x \\ y \\ z \end{pmatrix}$
3D vertex

```
// transform vertex
for (i=0;i<nMax;i++)
{
    temp[i] = H*vertex[i];

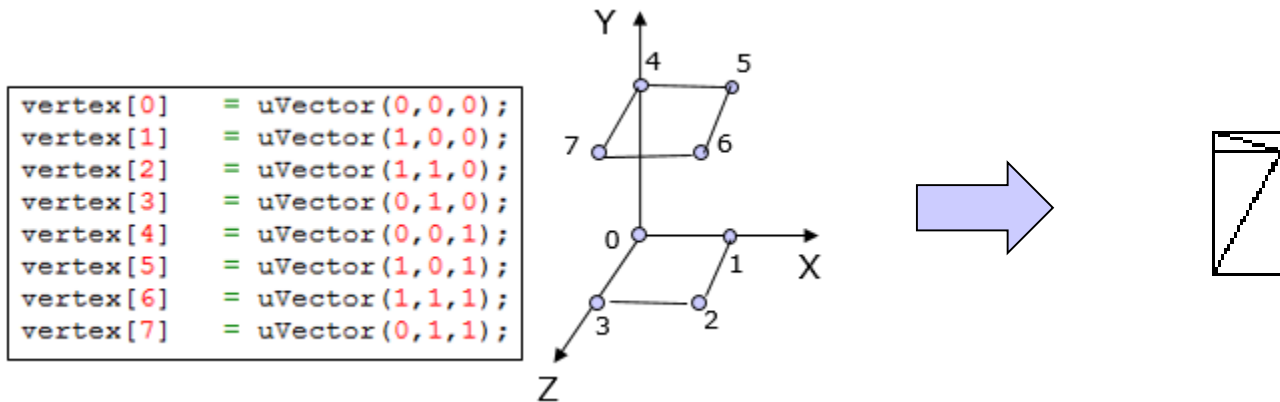
    float z = temp[i].z;
    temp[i] = P*temp[i];
    temp[i].x = -temp[i].x/z;
    temp[i].y = -temp[i].y/z;
    temp[i].z = -temp[i].z/z;

    temp[i] = S*temp[i];
}
```

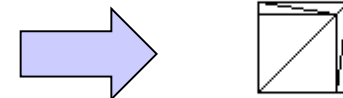
$\begin{pmatrix} x' \\ y' \\ 1 \end{pmatrix}$
2D temp



Why Width and Height are Different?



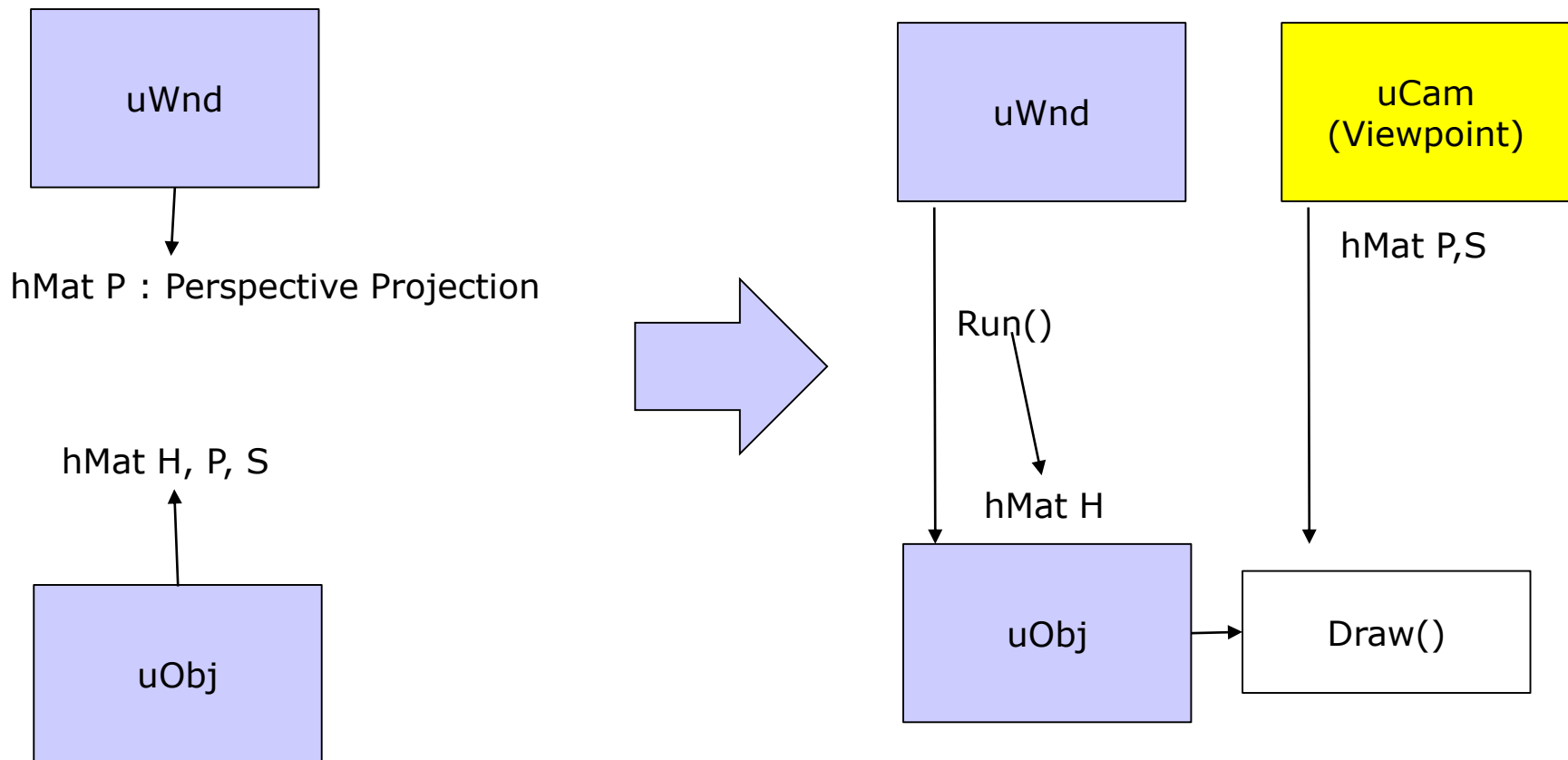
- Answer: That is aspect ratio.
- Windows CDC already changes aspect ratio
- Thus, modify aspect ratio=1



Ex) uWnd-20-3D-PP-Camera

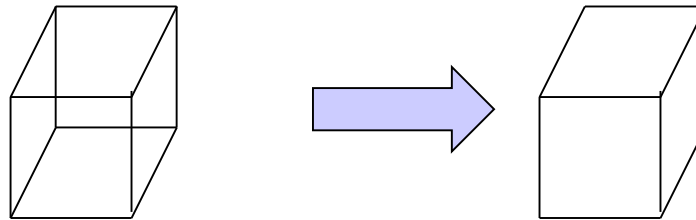
New Class: uCam for projection

- Think, this structure is somewhat bad.



Next week

- Hidden surface removal



- Various types of Objects

